

3D Printing

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September 28, 2013

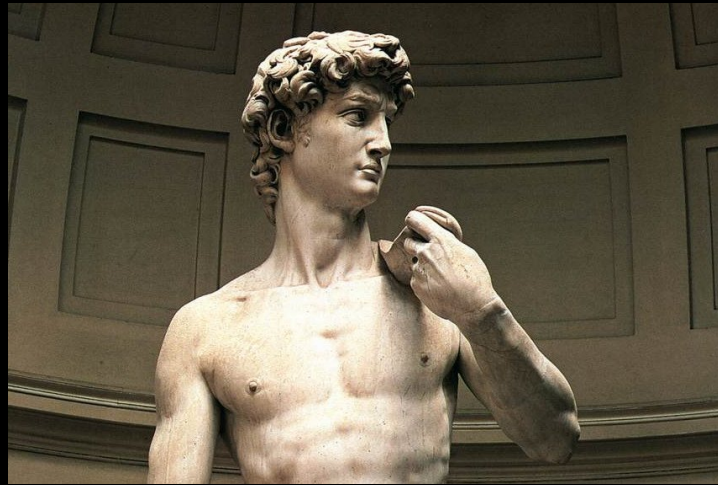


University of Kentucky
Electrical & Computer Engineering

How To Make Stuff

- People used to make things by hand...
but **humans make and use tools**
 - Most tools are special purpose;
they only make a particular type of thing
 - Using **computer control** we can build
smart, generic, tools –
even tools that can build themselves
(**RepRap**: Replicating Rapid prototyper)

Subtractive Building



"Every block of stone has a statue inside it and it is the task of the sculptor to discover it."

– *Michelangelo*

Subtractive 2D



- **Cutter:** cuts 2D material in any pattern
- **Paper/Craft:** paper moves in Y, knife in X
- **EDM/Laser:** X/Y bed, vaporizes material

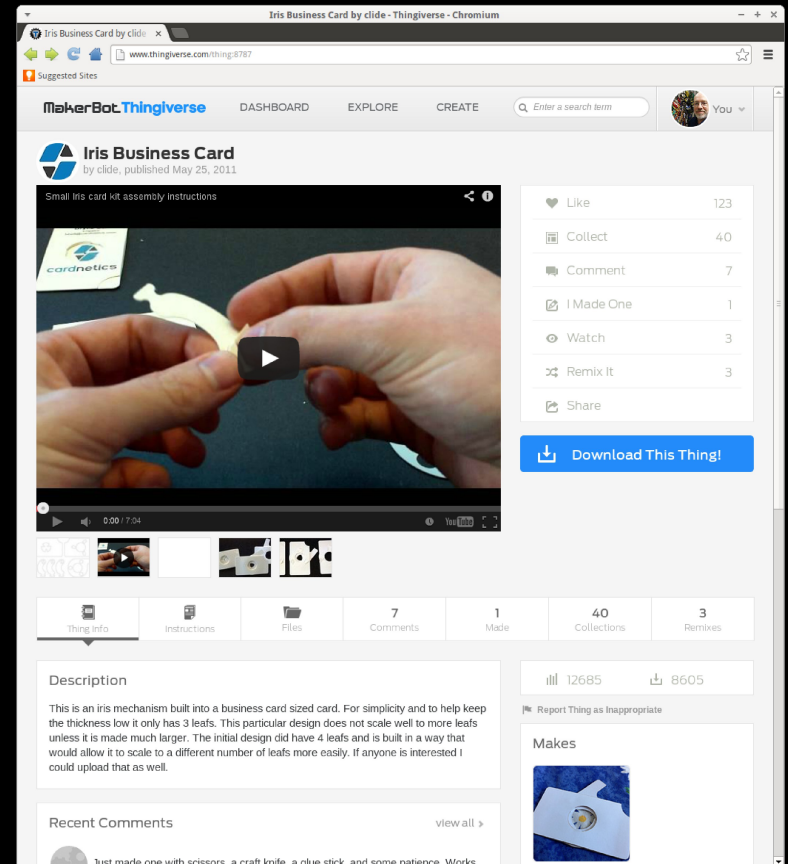
Subtractive 3D



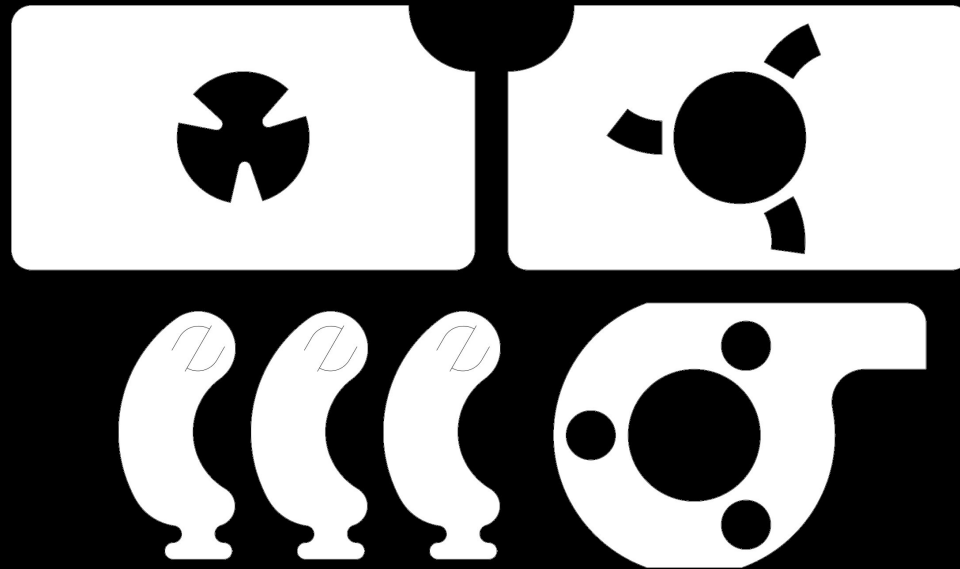
- **CNC**: Computer Numerical Control
- **Mill/Router**: part on X/Y bed, bit on Z axis
- **Lathe**: spins the part against a cutter

Making The Iris Card

- Subtractive 2D
- A working aperture iris made of card stock
- Design from **Thingiverse:**
Thing 8787

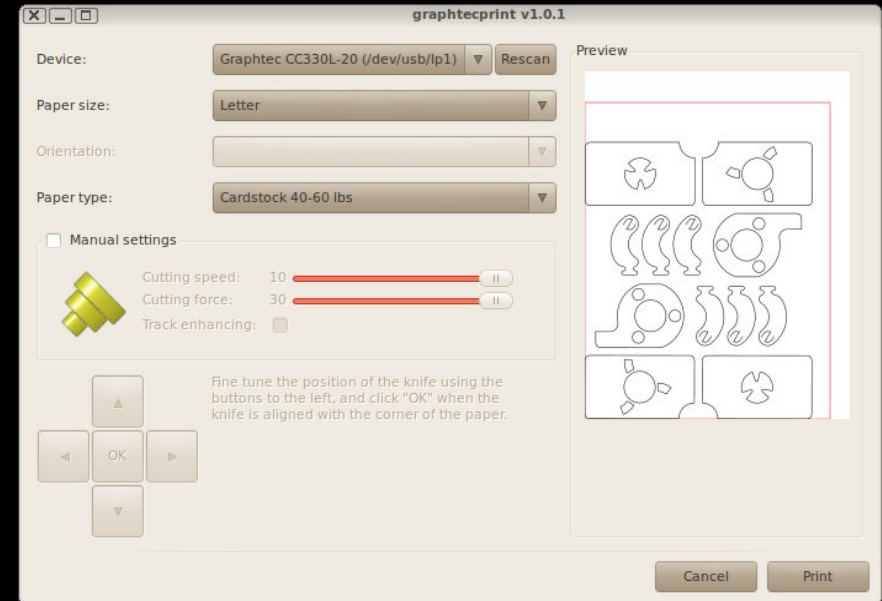
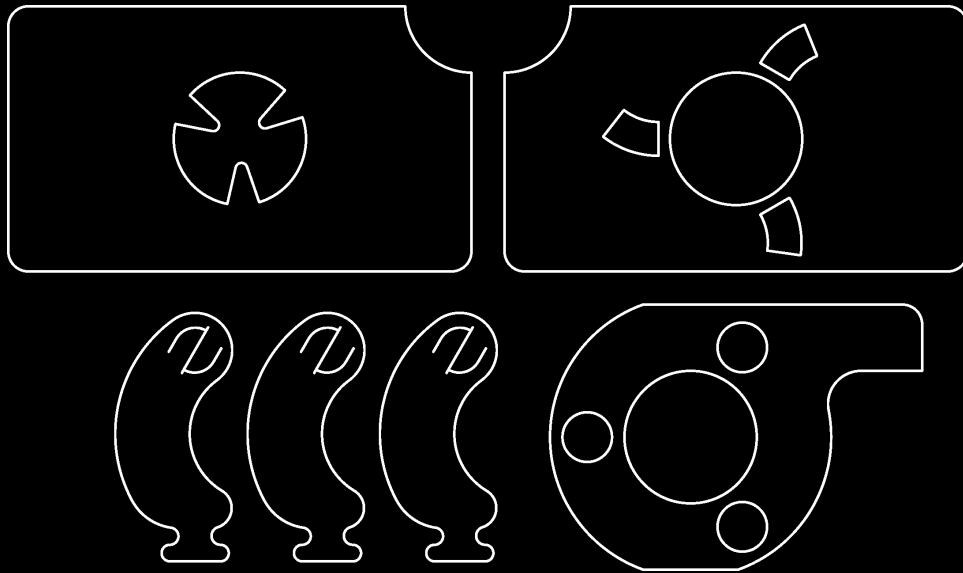


Making The Iris Card



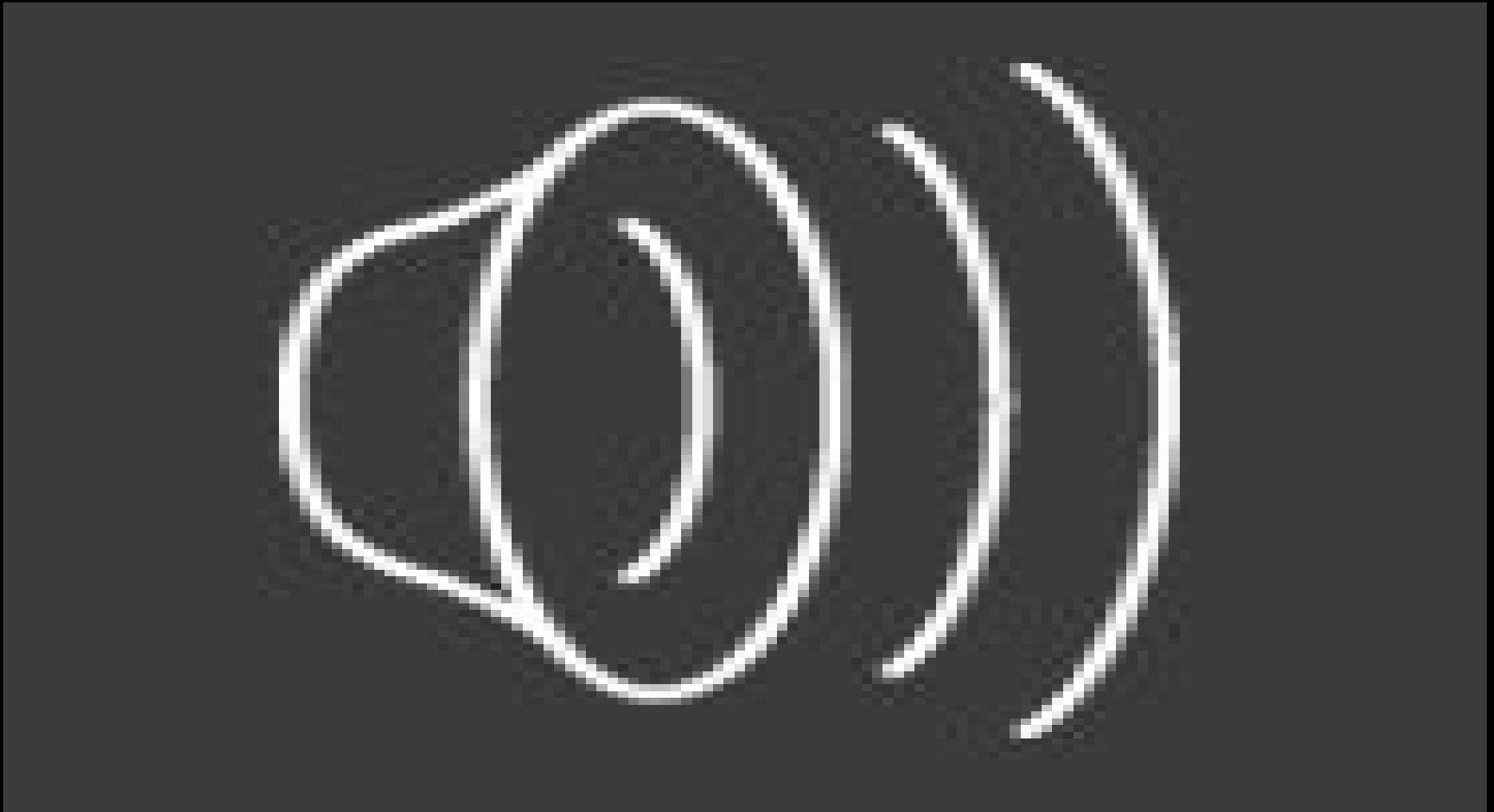
- There are just 6 parts to make & assemble
- Assembly involves folding & tape/glue
- The design is an **SVG** or **PDF** file

Making The Iris Card



- Cutting pattern ***must be straight lines...***
- Used **inkscape** to fix & arrange objects, **graphtecprint** to print

Making The Iris Card



Additive Building

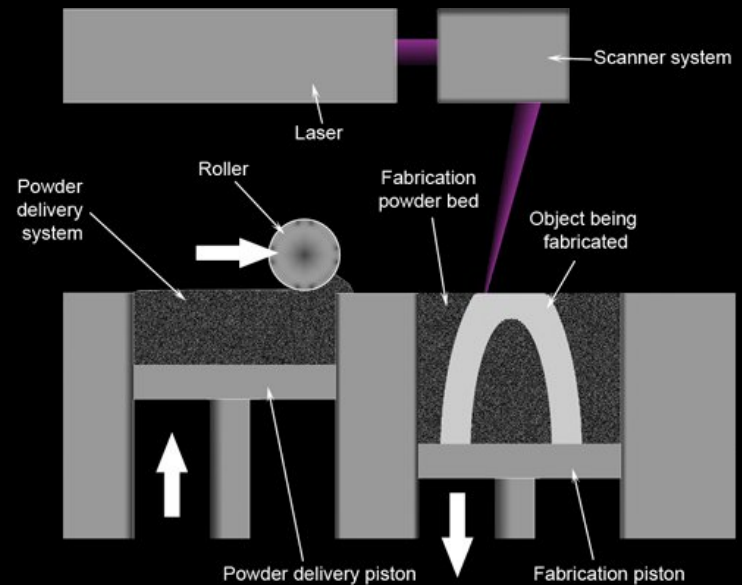
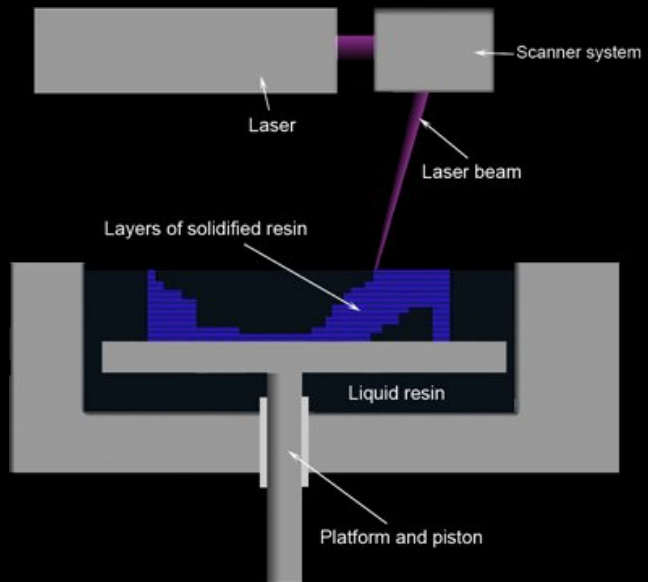


“The whole is greater than the sum of its parts.”
– *Aristotle*

Additive 3D Building

- Material is deposited, not taken away
- Only works with specific materials
 - powders or paper
 - curable photopolymer liquid resin
 - extrudable materials (mostly plastics)
- No need to get tool around material; can build things with internal structure
- Simpler “clamping” of the part

3D With Lasers



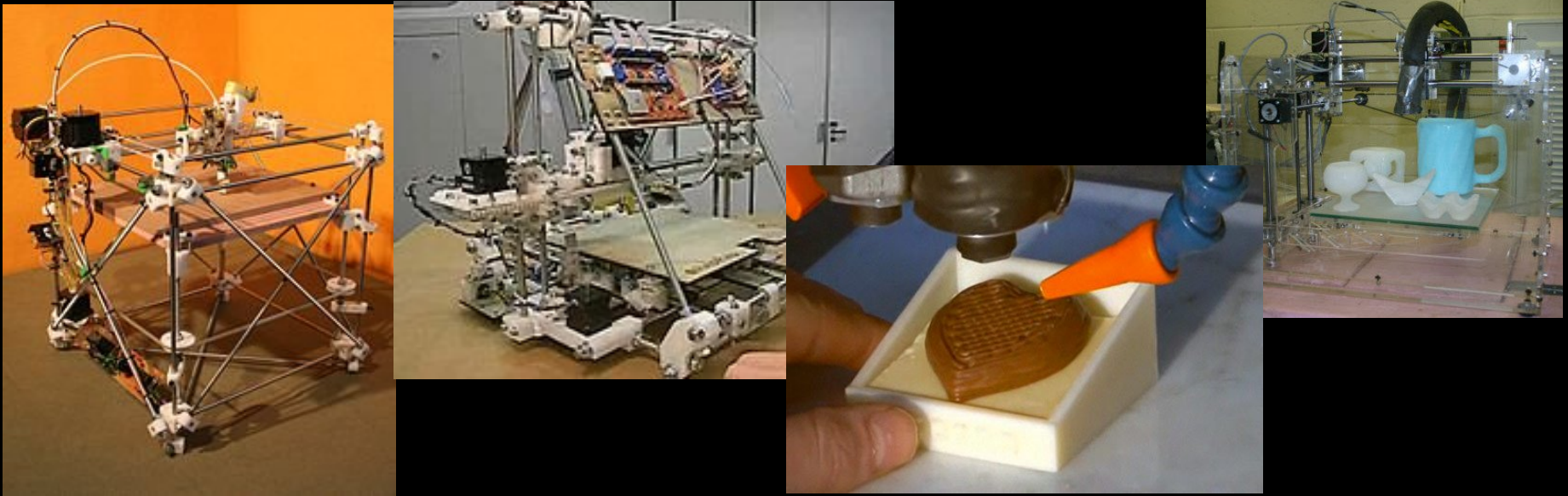
- **SLA:** Stereolithography of photopolymer
- **SLS:** Selective Laser Sintering of powder
- **SLM:** Selective Laser Melting of powder

3D With Glue



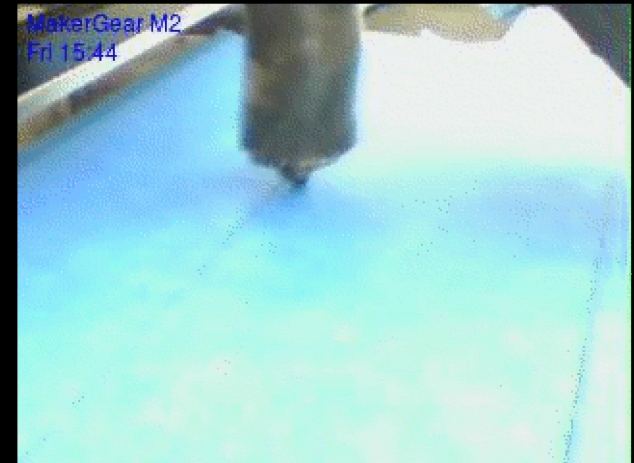
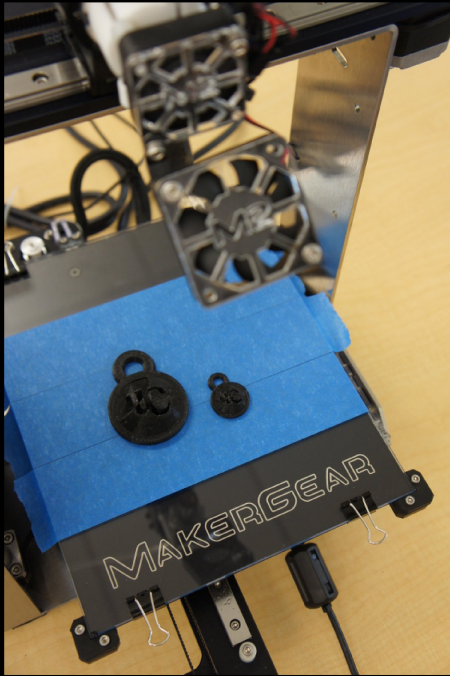
- Layers of paper: printed with glue & cut
- Layers of powder: printed with glue
- Can also be printed in full color

3D Extrusion (**RepRaps**)



- **FDM**: Fused Deposition Modeling
- **FFF**: Fused Filament Fabrication
- Typically **ABS** or **PLA** plastic filament...
but chocolate, water, etc. can be extruded

Our 3D Printer

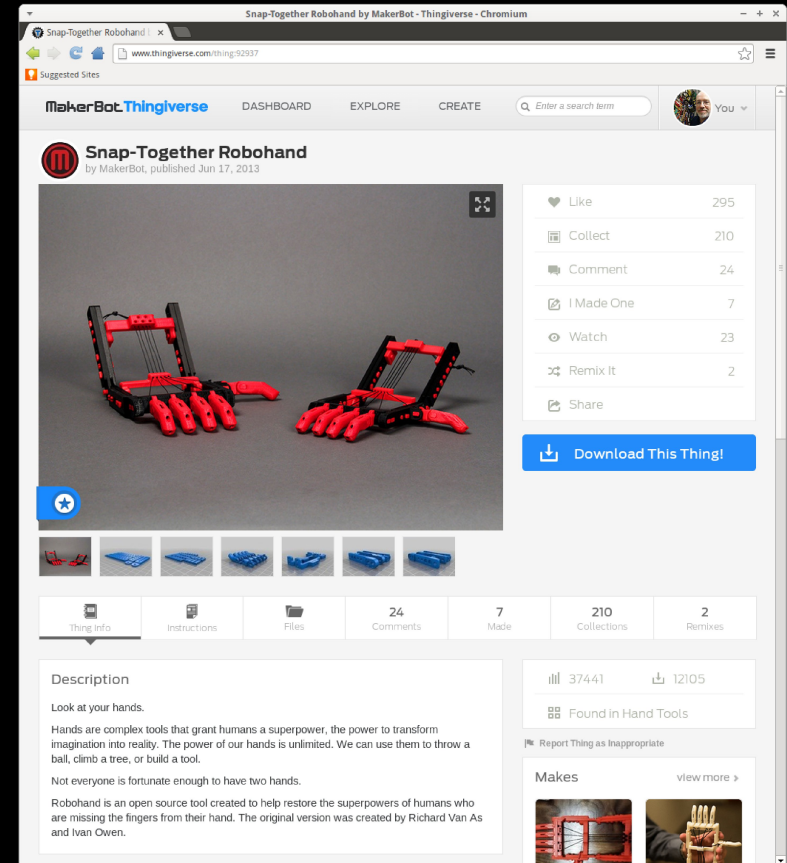


- It's a **MakerGear M2**, cost about \$1700
- We extrude 1.75mm diameter PLA filament to make **0.25mm** tall “threads”
- PLA extrudes around 180° – 210° C
- No clamping; **extrusion bonds to hot bed**

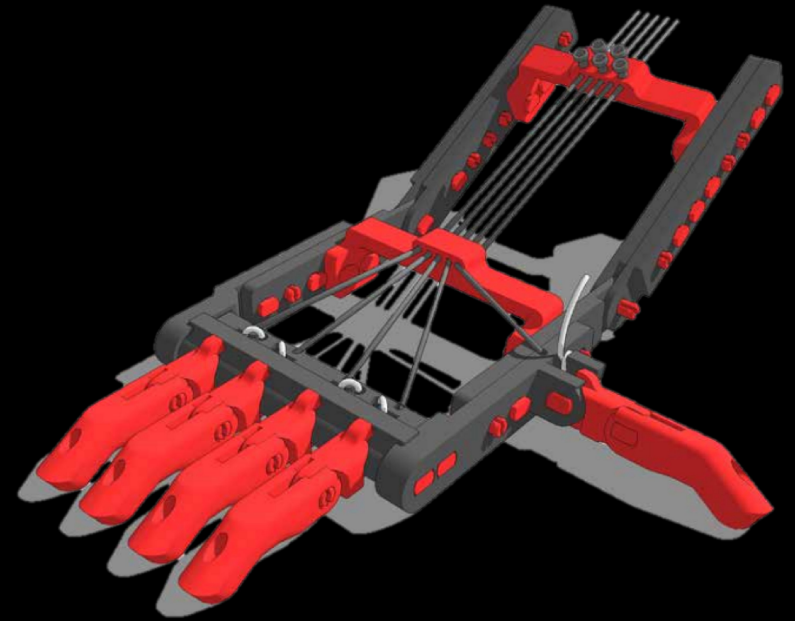
Making A Prosthetic Hand

- Additive 3D
- A working prosthetic hand driven by strings
- Famous design from

Thingiverse:
Thing 92937



Making A Prosthetic Hand



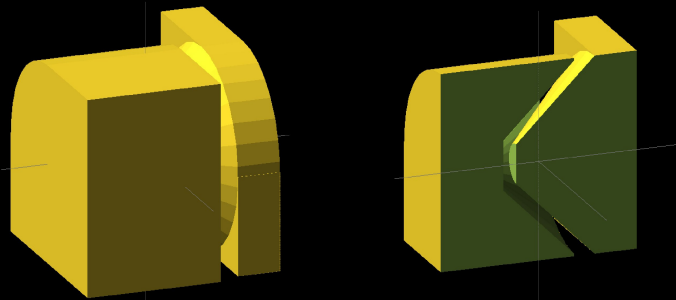
- Start with **Thing 92937**
- It takes about **6 hours to print**
- It takes **3-4 hours to assemble 50+ parts**

Making *The* Prosthetic Hand

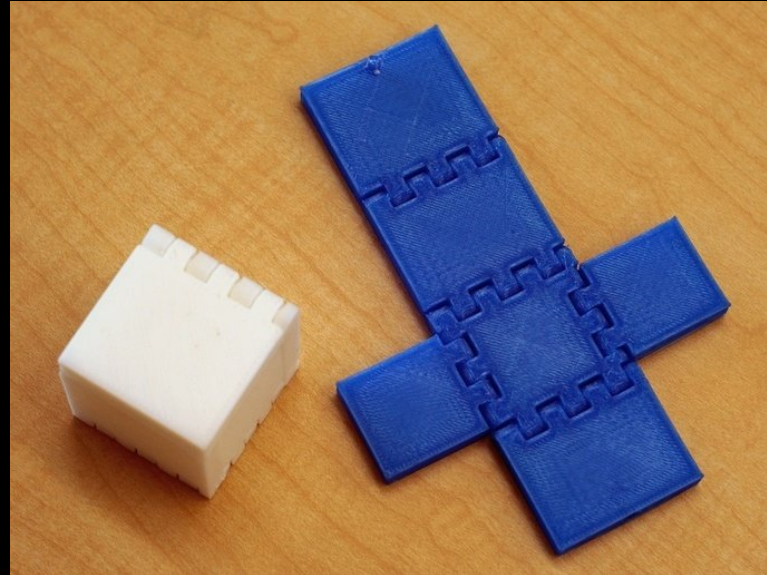
- Let's *not* start with **Thing 92937** ...
- Redesign from scratch with goals:
 - **Faster print time** – under 1 hour
 - **Print assembled** – no snap together parts
 - **Better match scale of actual hand**
(sized to 18-month-old girl's hand)
 - **Minimum cost** – about \$1 total

How Do We **Print Assembled**?

- Easy if no moving parts, right?
 - Can't have **unsupported spans**
 - Can't have **angles shallower than 45°**
- How do we print an assembled joint?
Fortunately, I made this hinge:

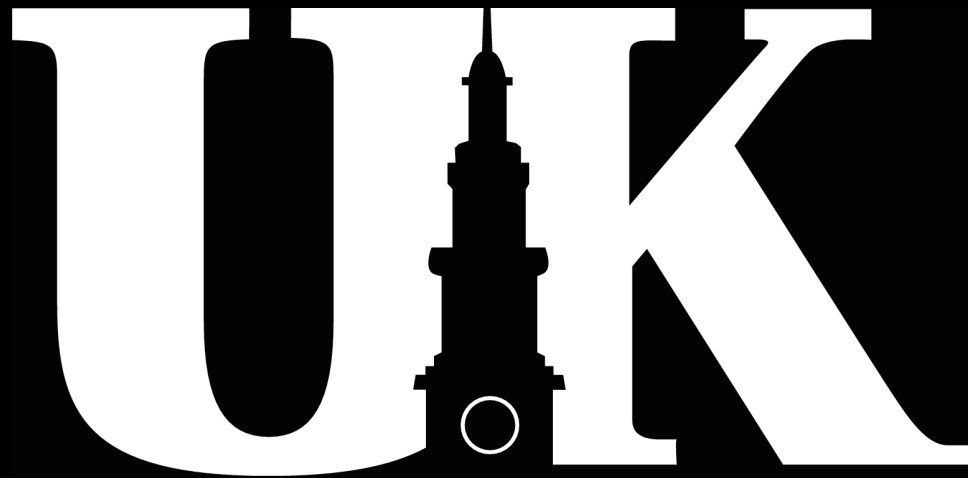


Making The HingeBox



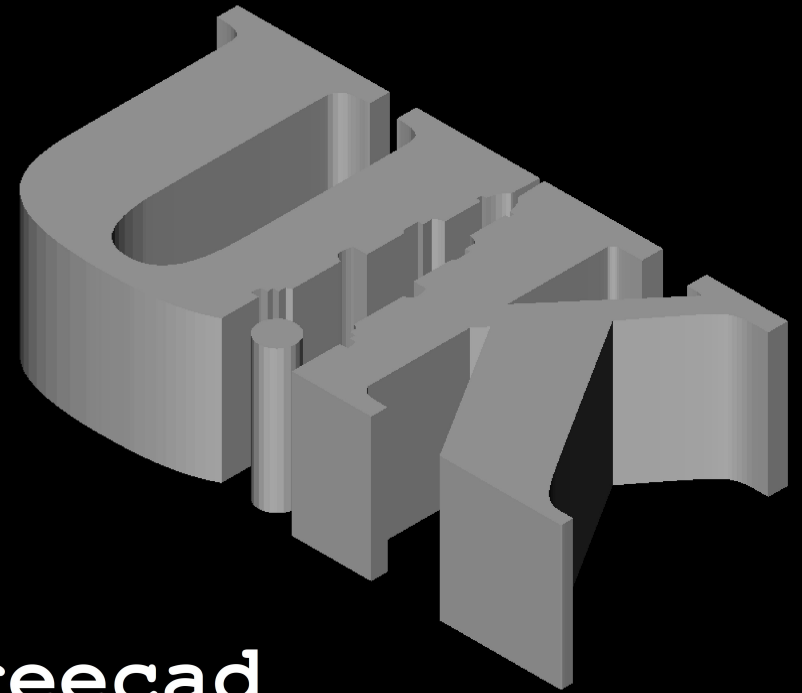
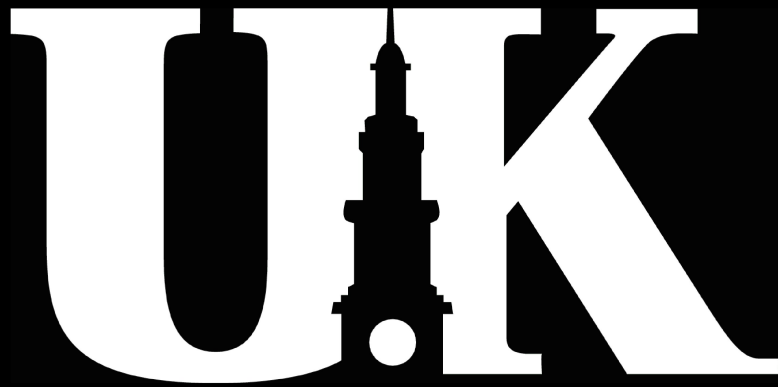
- Created a *hinge library* in openscad
- The HingeBox is just a bunch of hinges imposed on two “cubes” plus a latch

Put A UK Logo On It



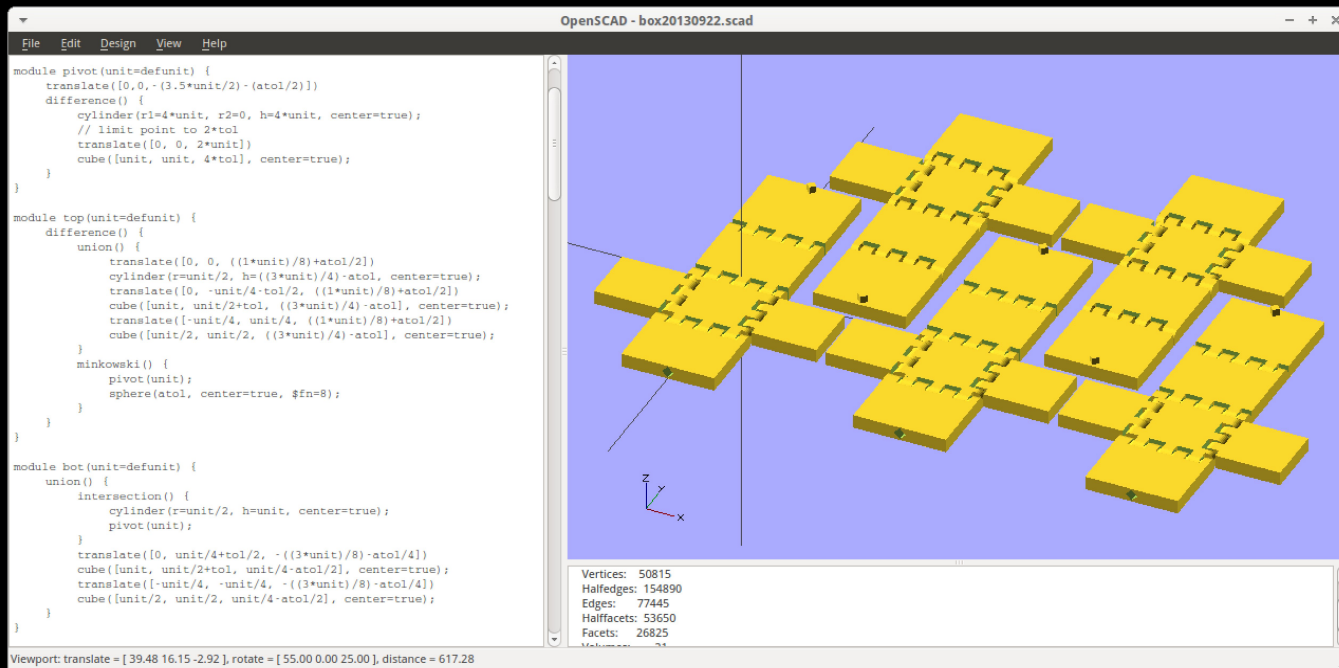
- Start with UK logo
- Use `gimp` (an image editor) to simplify it
- Use `inkscape` to convert it to **DXF** vectors

Put A UK Logo On It



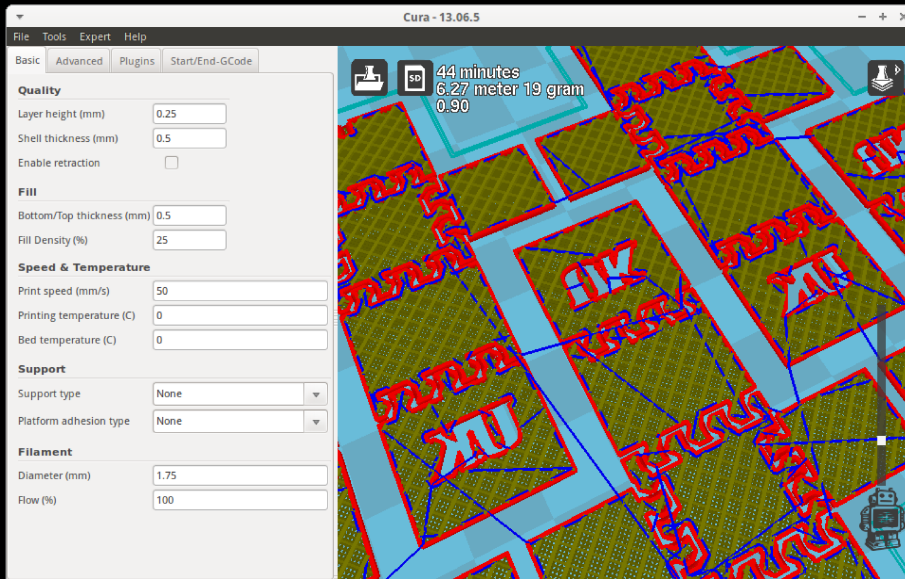
- Load the 2D **DXF** into `freecad`
- Extrude it to make a 3D **STL** file
- Use `openscad` to “union” or “difference”

Making The Hinge Box



- An openscad 3D model is a *program* constructing objects from simple shapes
- Output is an **STL** model

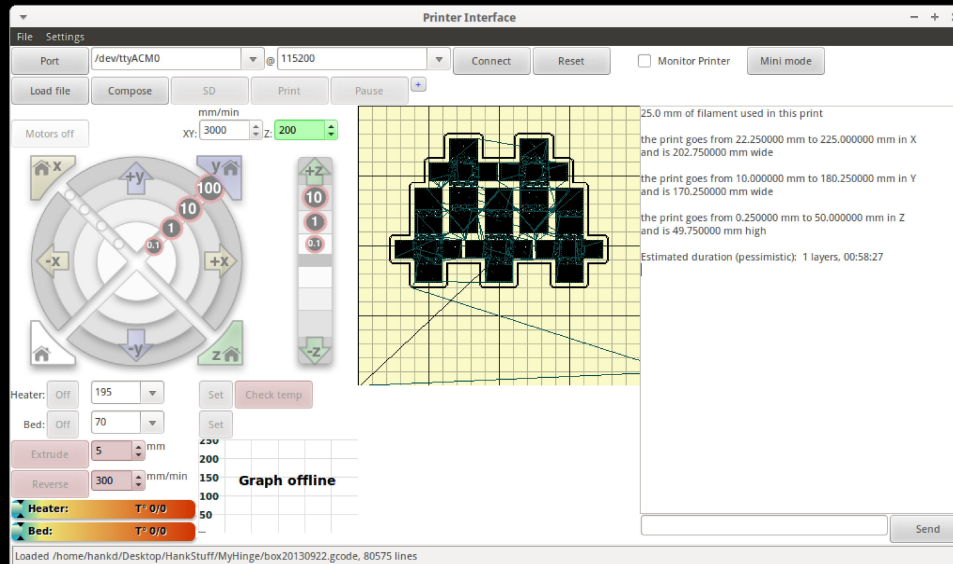
Making The Hinge Box



```
G1 X90.062 Y143.899 E2.97592
G1 X89.502 Y143.229 E3.05532
G1 X88.872 Y142.279 E3.15897
G1 X88.262 Y141.249 E3.26782
G1 X87.812 Y140.339 E3.36013
G1 X82.282 Y126.599 E4.70690
G1 X81.972 Y125.579 E4.80383
G1 X81.432 Y123.169 E5.02841
G1 X81.332 Y122.429 E5.09631
G1 X81.242 Y119.949 E5.32196
G1 X81.252 Y119.199 E5.39016
```

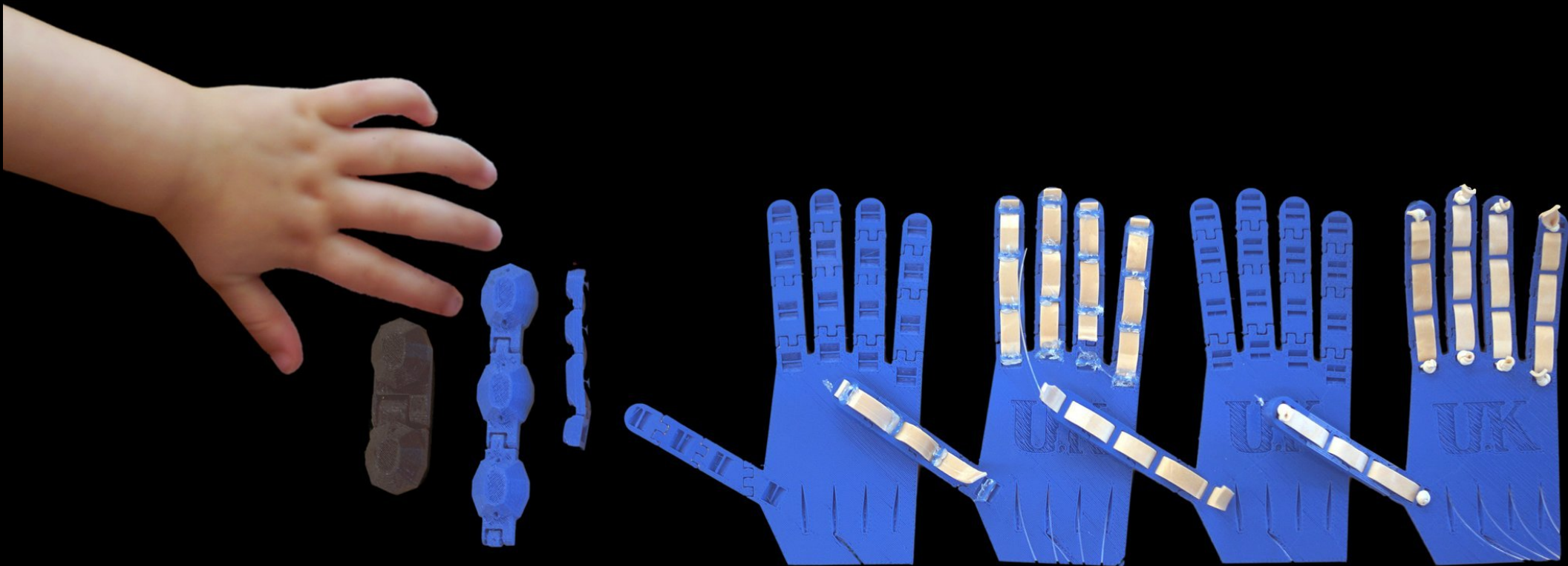
- The **STL** model is triangles on surfaces
- **Slice** the solid model using **cura**
- Output is **gcode** – lines in X,Y,Z,E

Making The Hinge Box



- Print **gcode** using **pronterface**
- **Wait for it...**
- Finished part comes off the cooled bed

Making The Prosthetic Hand



- Did not get it right on the first try...
- Isn't that what rapid prototyping is all about?

How Does It Work?

- Each finger has **3 joints** (hinges) that can bend up to 90° to grasp things
- The thumb also has **3 joints**, but **one is angled** to bring the thumb into opposition
- A **rubber band** on the back of each finger resets to relaxed non-grasping position
- **Fishing line** through the fingers and palm is the muscle that pulls the hand closed

```

module fingertip(wide=10, long=11, thick=6) {
// make a finger segment
assign(inset=1) // inset of top of finger
assign(bandwide=6+2*tol) // width of rubber band
difference() {
hull() {
// bottom of segment
translate([0, long/4, 0])
cube([wide, long/2, thick/2], center=true);
translate([0, (long-wide)+wide/2, 0])
cylinder(r=wide/2, h=thick/2, center=true);

// top of segment
translate([0, wide/2, thick/2])
cylinder(r1=wide/2, r2=wide/2-inset, h=thick/2, center=true);
translate([0, (long-wide)+wide/2, thick/2])
cylinder(r1=wide/2, r2=wide/2-inset, h=thick/2, center=true);
}

// hole for muscle wire
translate([0, long, thick/4+sqrt(2)])
rotate([90, 0, 0])
cylinder(r=1, h=long*2, center=true, $fn=4);

// spot to tuck end of muscle wire
translate([0, long, thick/4+sqrt(2)])
rotate([90, 0, 0])
sphere(r=2, $fn=4);

// loop for rubber band
translate([0, long-thick/2-(bandwide/2*sqrt(2))/2, -thick/4])
difference() {
rotate([0, 90, 0])
sphere(r=bandwide/2*sqrt(2), $fn=4);
translate([0, 0, -sqrt(2)*bandstrap])
rotate([0, 90, 0])
sphere(r=bandwide/2*sqrt(2)+0.001, $fn=4);
}
}
}

module finger(wide=10, long=11, thick=6, nofing=0) {
assign(firstlong=1*long)
assign(twolong=1.25*long)
assign(tiplong=1.25*long)
union() {
if (nofing == 0)
translate([0, wide+thick/4+tol, 0])
union() {
translate([0, firstlong+thick/2+2*tol, 0])
union() {
translate([0, twolong+thick/2+2*tol, 0])
union() {
hingelen(wide, thick/2);
translate([0, thick/4+tol, 0])
fingtip(wide, tiplong, thick);
}
}
}
}
}
}

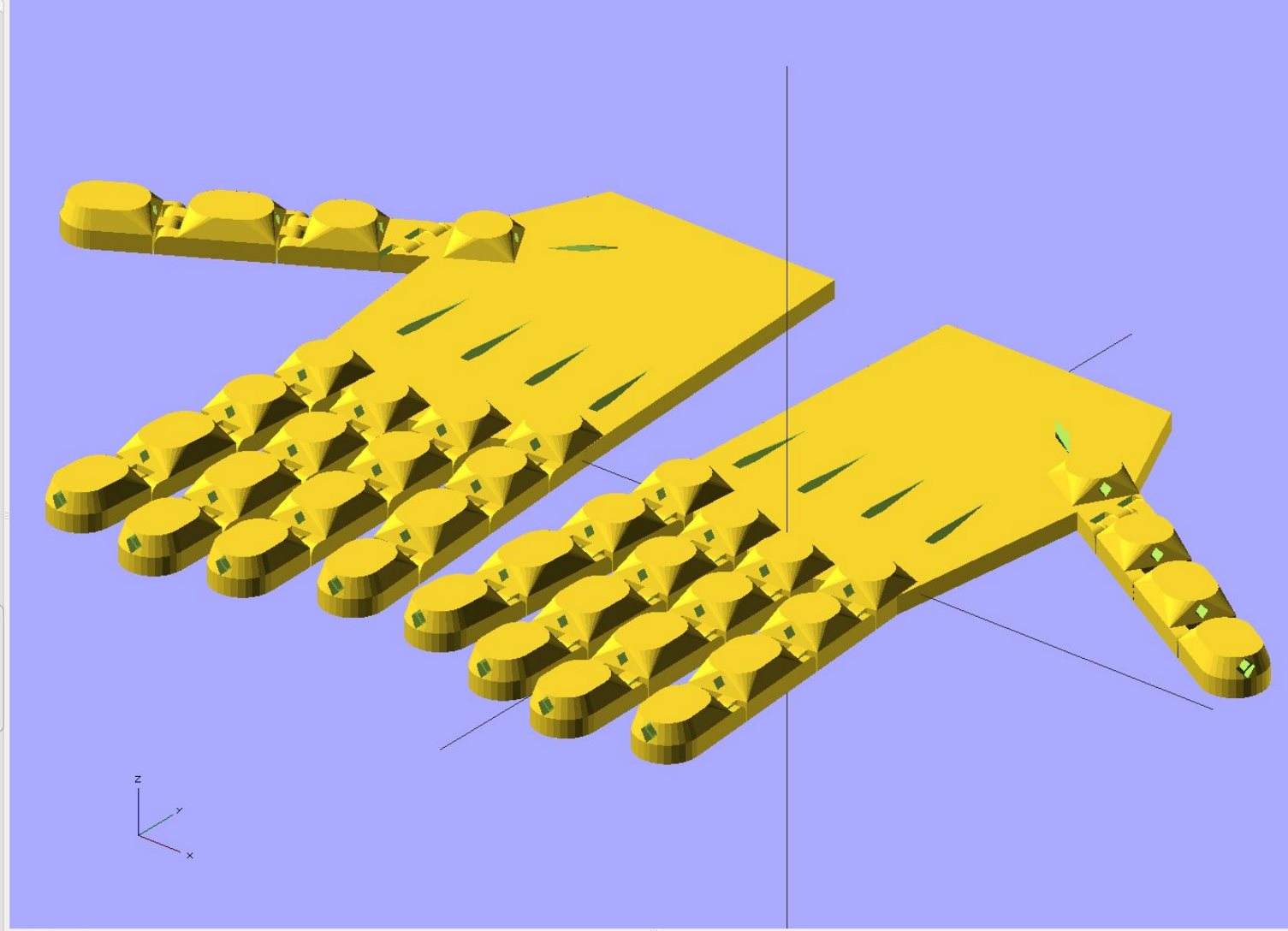
hingelen(wide, thick/2);
translate([0, thick/4+tol, 0])
fingseg(wide, firstlong, thick);

}

difference() {
// hand base
fingseg(wide, wide, thick);
translate([0, -wide, 0])
cube([2*wide, 2*wide, 2*thick], center=true);
}
}

module thumb(wide=10, long=11, thick=6) {

```



varea: yes
 Vertices: 30104
 Halfedges: 99064
 Edges: 49532
 Halffacets: 39020
 Facets: 19510
 Volumes: 39
 Total rendering time: 0 hours, 20 minutes, 0 seconds

Making The Prosthetic Hand



- Check all hinges are free to move
- Insert rubber bands on backs of fingers:
Cut band, **knot** one end & trim the other,
work through slots & tighten, **knot** & trim
- **Route fishing line through fingers:**
Push line through palm & finger, **knot** end at
finger tip, trim after about two hand lengths

Questions?



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